

Underground Workings Detection at the Fimiston Open Pit KCGM

By

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Underground Workings Detection at the Fimiston Open Pit KCGM

- A Joint Venture between Newmont Australia and Barrick Gold of Australia
- Produces 800,000 gold ounces annually.
- ❖ The total movement is about 84 Mt per annum
- The current pit is about 2.5 km long, 1.2 Km wide and 300 metres deep.
- The ultimate pit will be about 3.6 km long, 1.5 km wide and 600 m deep.





Underground Workings Detection at the Fimiston Open Pit KCGM

- Open pit is mining in the area called Golden Mile with over 100 year mining history
- ❖ > 3000 km old mine headings and over 700 stopes under the open pit area
- The stopes extend to over 1000 m below surface level

Kalgurli Shaft 11th Kalgurli Lake View 6- Star Shaft LVLS Main Shaft B Perseverance Jimiston Post Office Oraya Small & Treatment Plant GMK Treatment Plant KOT. Sth. Kalgurli Shaft Sth. Kalgurli Svanhoe Shaft LVs S. Pemerby Short ONB Associated Short GMK. Treatment Plant LVLS. Chaffers Short LVLS. Edwards Short LVLS Menty's Short Joiling Dump 68P Treatment Plant (defunit) Kalgurii Est. Lone Shaft GBR Main Shaft GBR Treatment Plant GBR

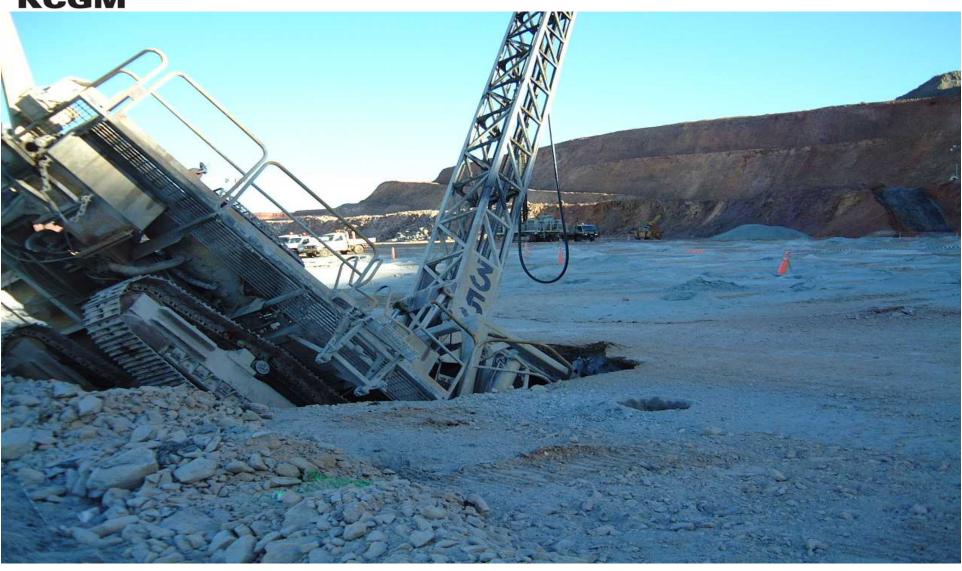




Planned subsidence by blasting







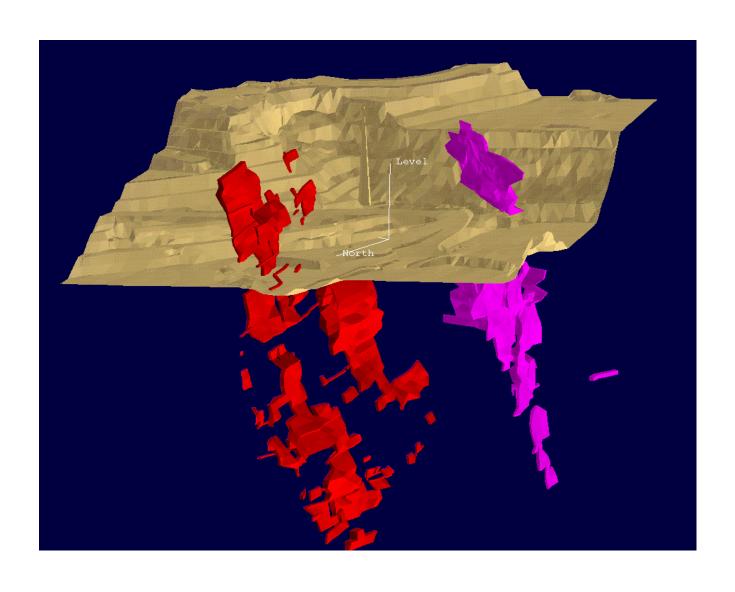


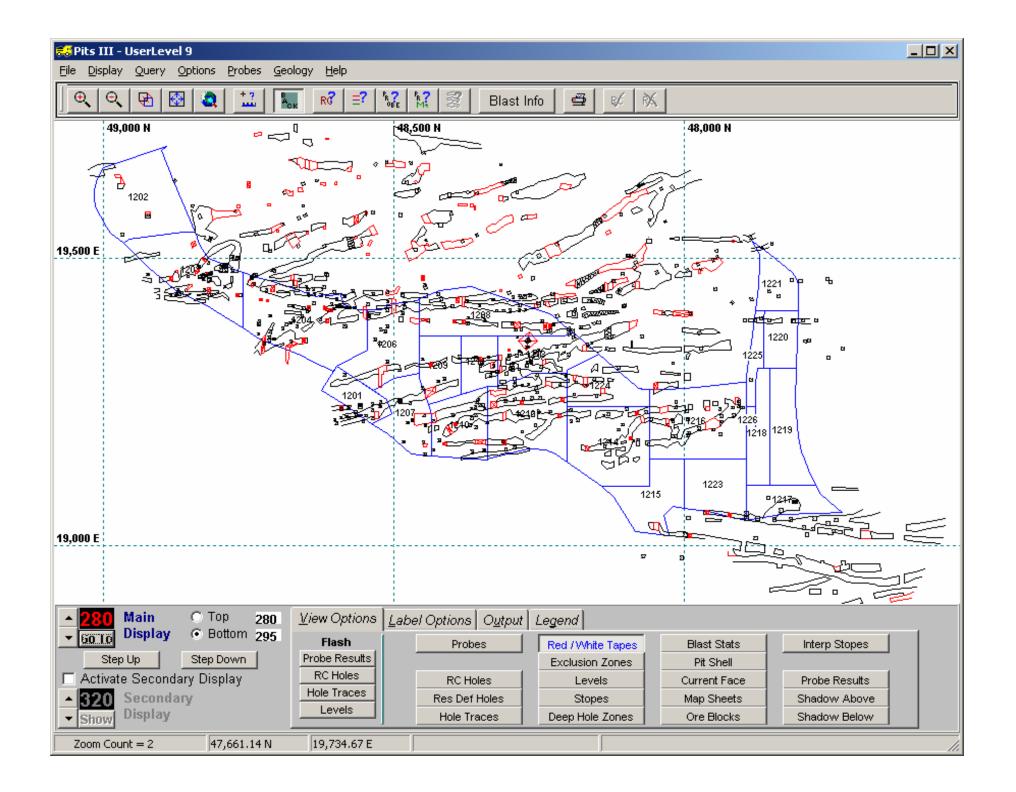
VOIDS MANAGEMENT

- All the old plans and sections have been digitised and can be displayed in 2D and 3D
 - Challenge the difference between old records and real situation!
 - Major problem was the lack of agreement on where North was!!!
- Procedures developed for mining through old workings
- Aiming for 'no surprise'



3D Model







UNDERGROUND WORKINGS FLAGGING

❖ Black/white tape

 Indicates a known area of underground workings that has low probability of developing a void to surface and is deemed safe for heavy vehicle access if equipped with a roll-over-protection system.

Red/white tape

 Indicates a known or suspected void area with insufficient cover. In other words, the area has a high probability of developing a void to surface.



UNDERGROUND WORKINGS DELINEATION and DETECTION

- Probe drilling
- * RC (reverse circulation) drilling
- Cavity Auto Laser Scanner (C-ALS)
- Geophysical methods

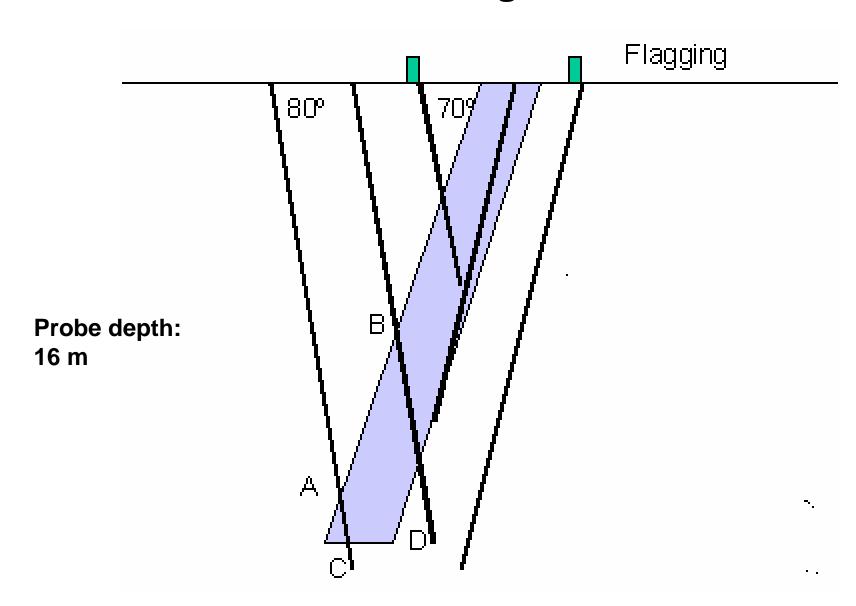


Probe Drilling





Probing





RC DRILLING

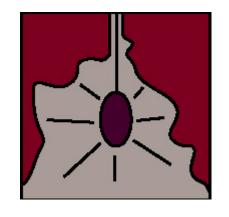
- ❖ RC holes are drilled for grade control at 8m x 10m pattern with 38 to 50 m depth in ore zones (stope areas) for grade control purpose.
- ❖ RC holes provide good information for void detection and delineation a few benches ahead.

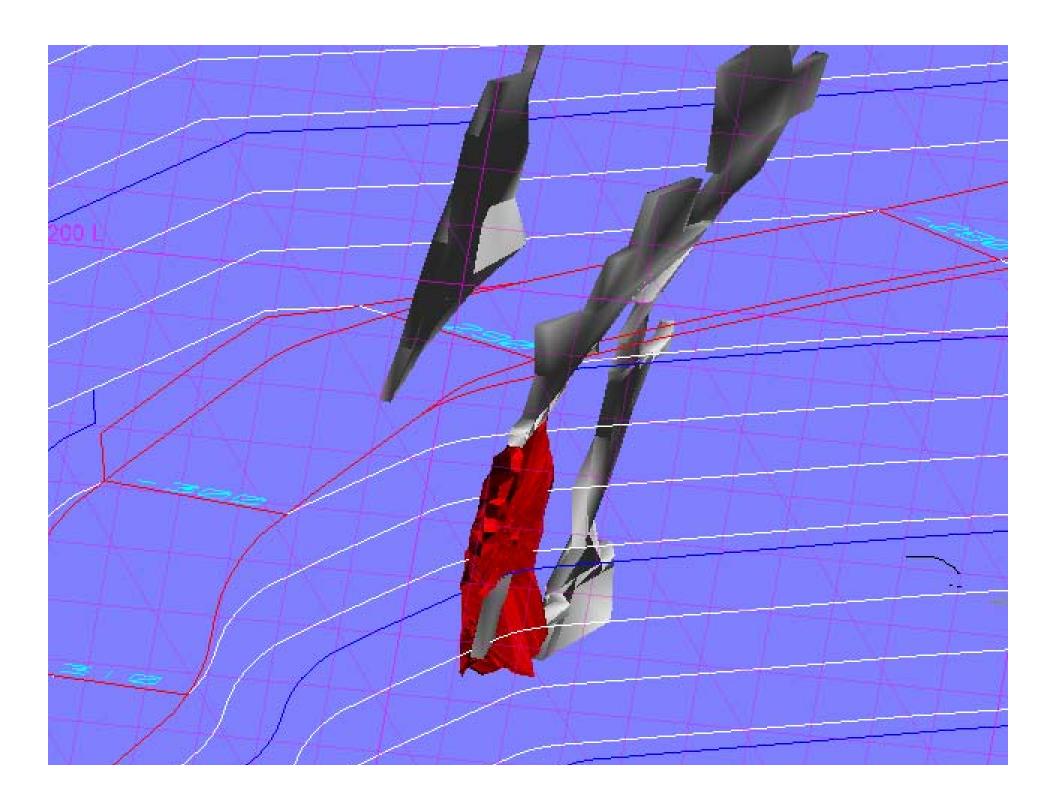


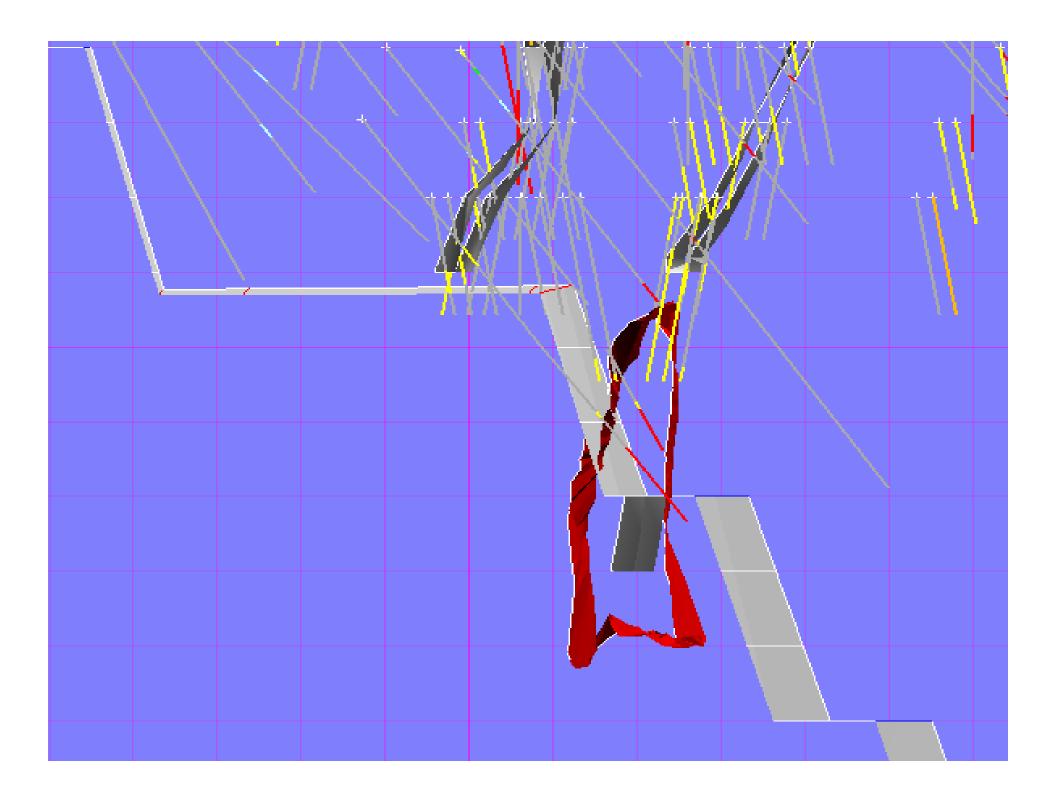
Cavity Auto Laser Scanner - provide 3D imagine













GEOPHYSICAL METHODS

Major methods trialed at KCGM

- Ground Probing Radar (GPR)
- Micro-gravity
- Resistivity imaging method
- Seismic tomography (surface)
- ❖ Transient Electric Magnetic (TEM)
- Cross-hole radio wave tomography



GPR

- ❖ Penetrating depth < 15m</p>
- **❖** Success rate 30 -70%
- **❖** 30% false anomalies
- **❖** Major difficulties:
 - Broken layer from subdrill (1-2 metres)
 - Saline water sprayed on ground for dust suppression
 - Complex ground condition, structures
 - Others unknowns
- **❖** Conclusion: easy to operate but not reliable

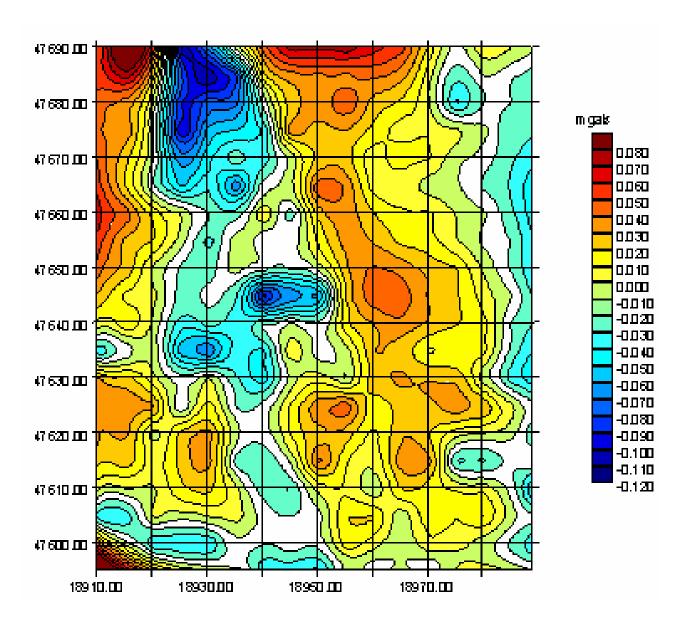


Micro-gravity

- Micro-gravity measures gravity at each monitoring station.
- Low gravity indicates mass loss -> void
- ❖ Pattern used 5m x 5m



Micro-gravity



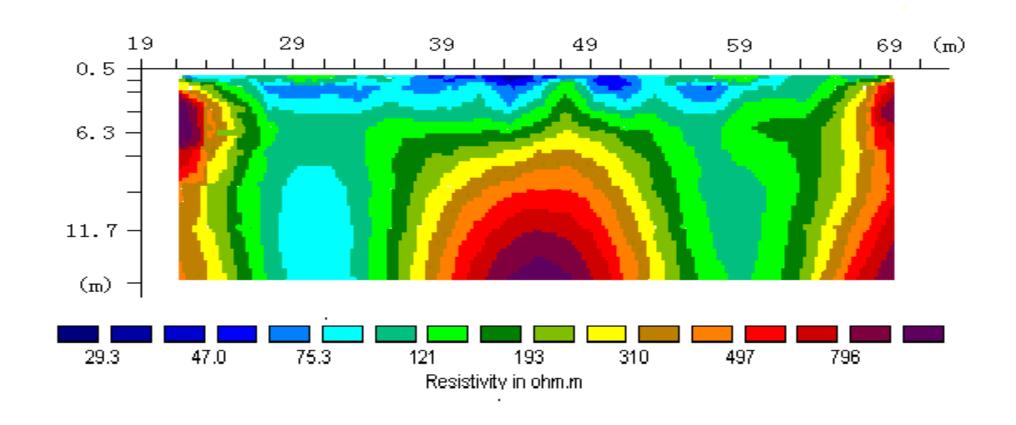


Micro-gravity

- **❖** Difficulties with Micro-gravity
 - Slow data acquisition: 10 stations per hour
 - Uncertain with the size, depth, width and dip direction
 - Slow data processing (Terrain correction)
- Suitable for void detection but not for delineation

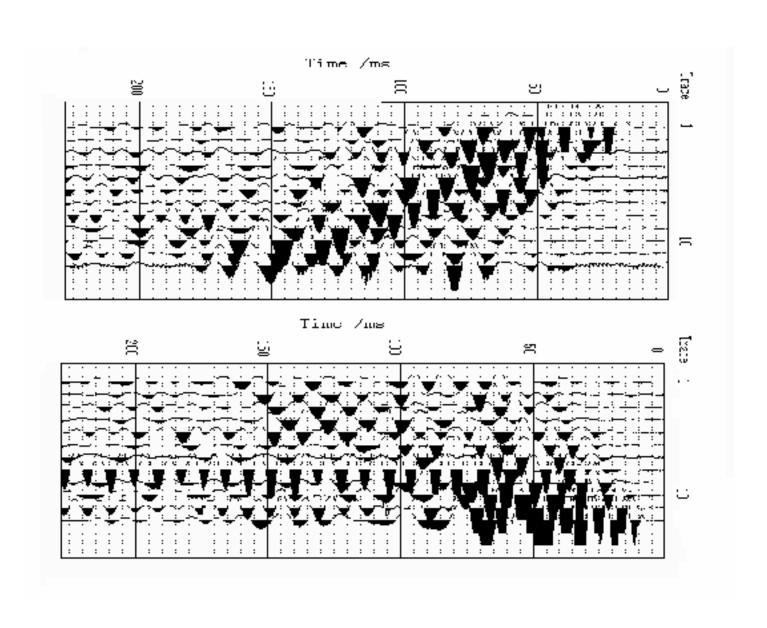


The Multi-Electrode Resistivity Method



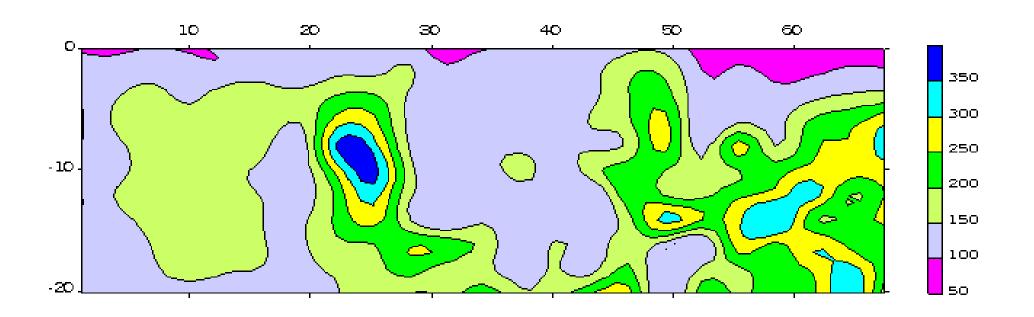


Seismic Tomography



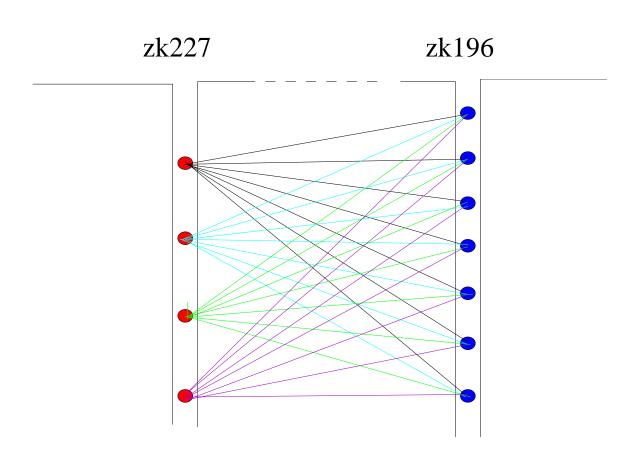


The Transient Electromagnetic Method (TEM)





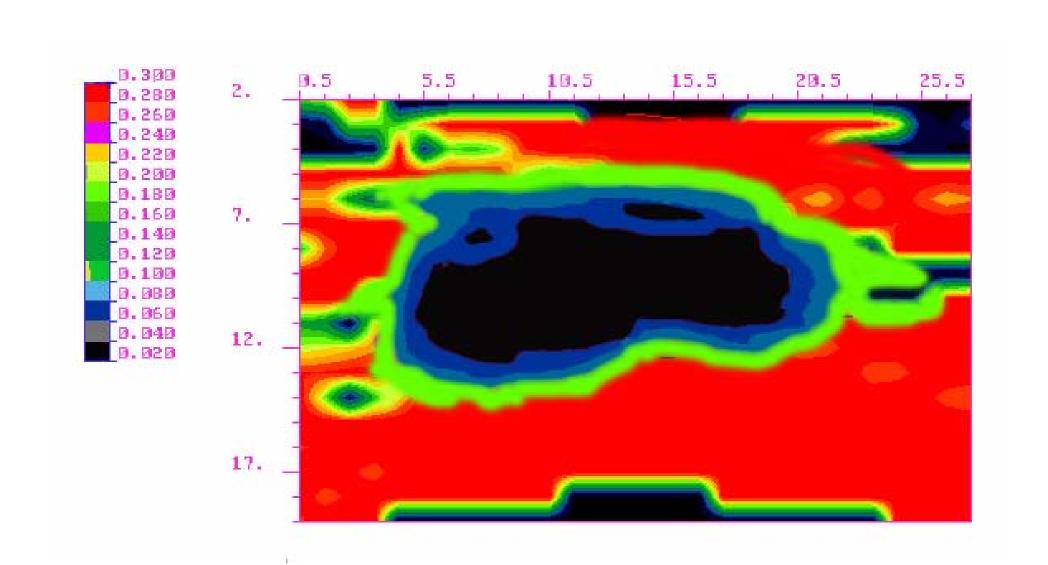
Cross-hole Radio Wave



- Receiver
- Transmitter



Cross-hole Radio Wave





Conclusions (at KCGM)

- Geophysical tools work well for ideal situation such as uniform material but not effective for mines with complex rock conditions
- Geophysical tools may be used for void detection (looking for surprise) but not for delineation
- Cavity Auto Laser Scanners are very useful for void mapping
- Probe drilling is the most reliable method for void delineation



End of presentation

Questions?